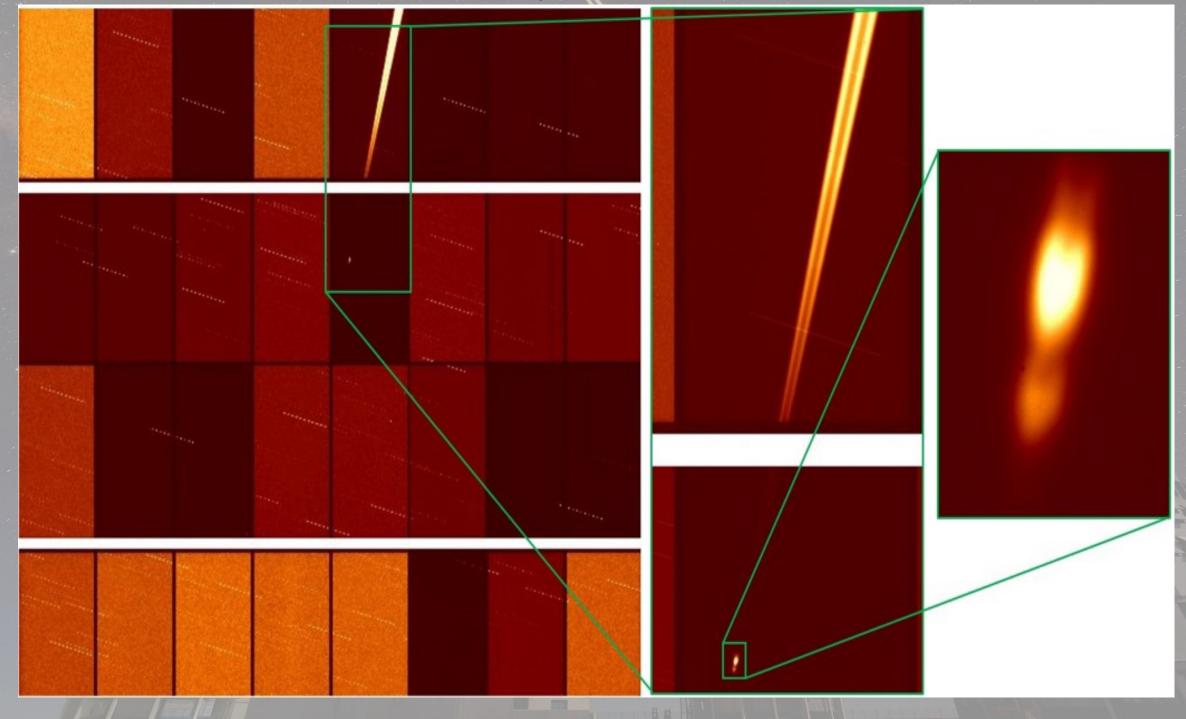




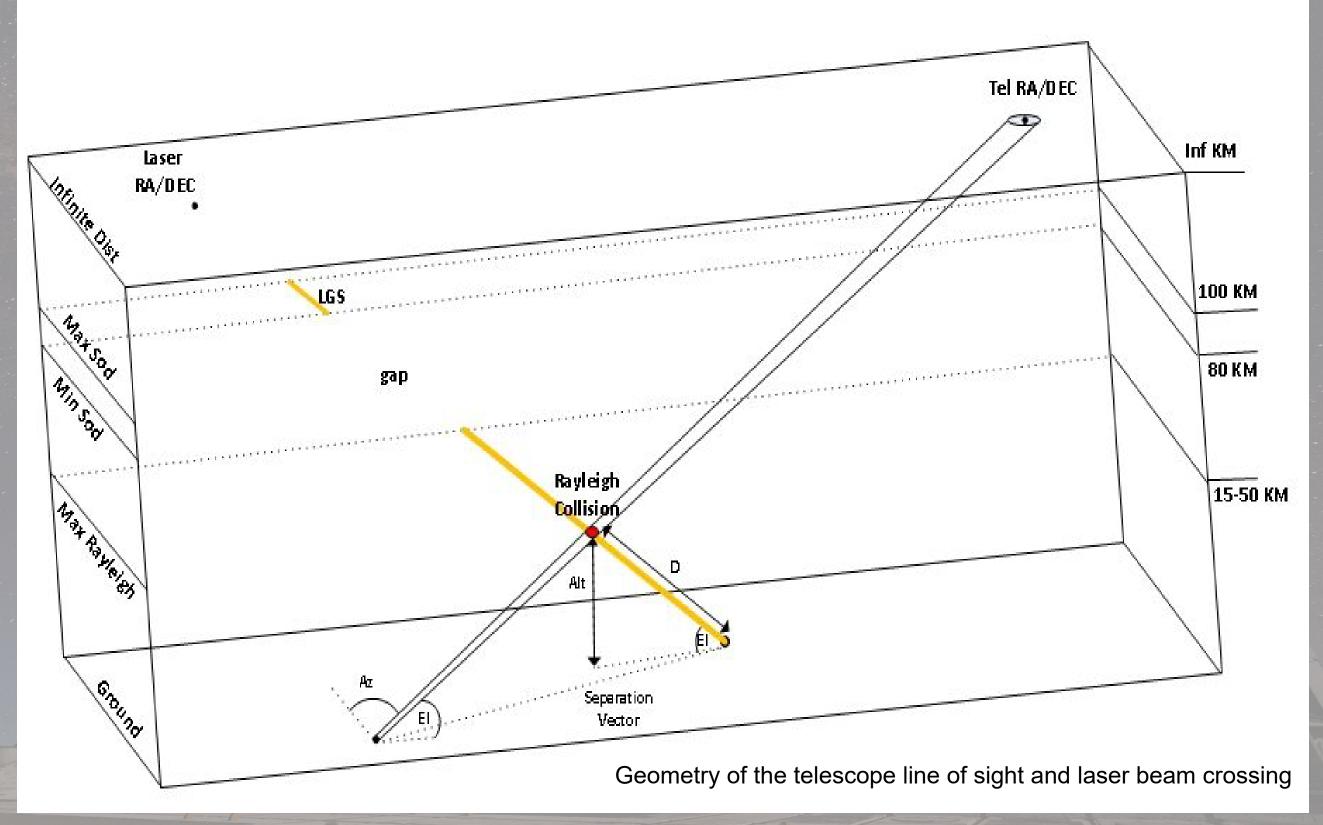
The effect of a laser collision

Example of 589nm laser contamination on OmegaCAM / VST



L4A0-13 - Jun 2019

What is the cause of a collision?



L4A0-13 - Jun 2019

. ES+

Why do we need a tool?

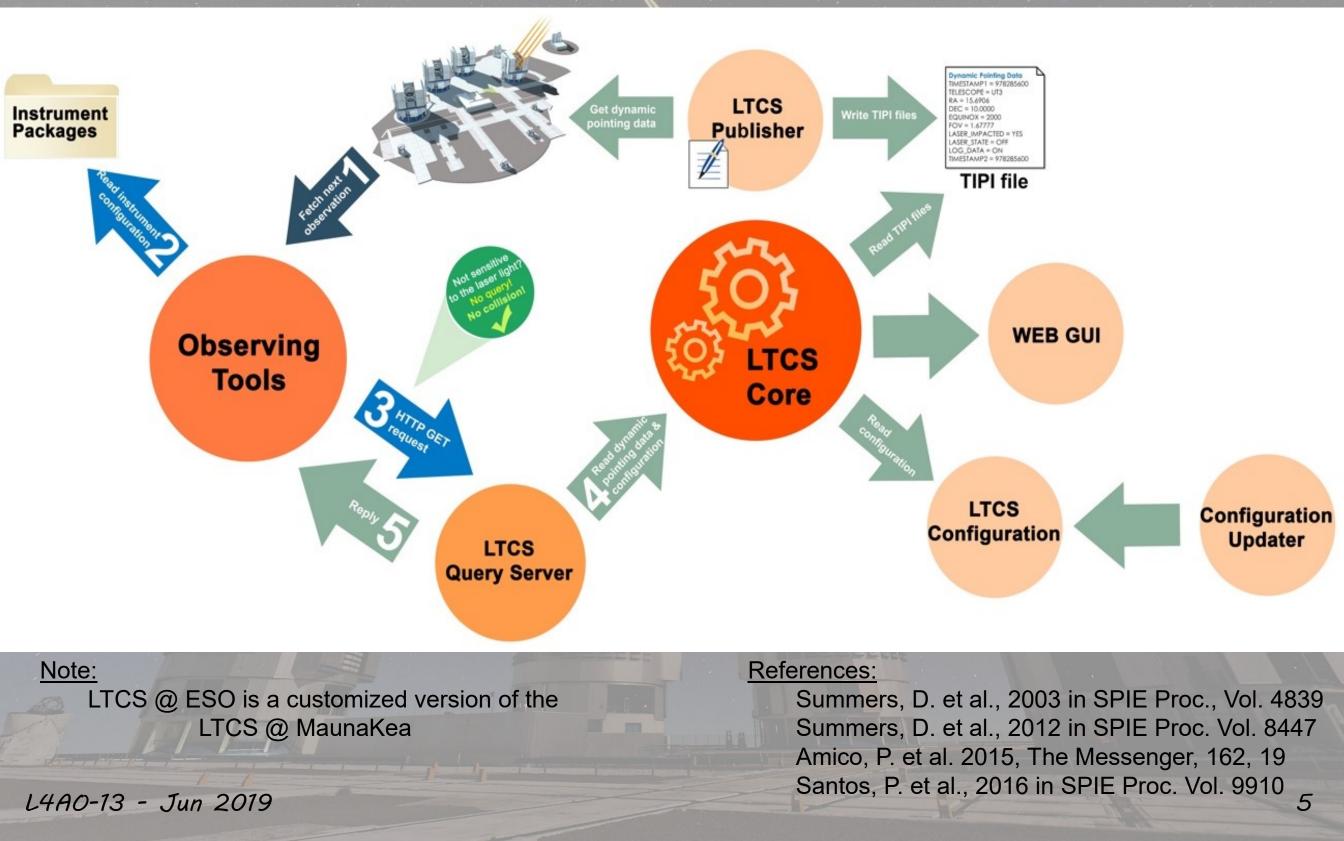
File S	Std. Options					Help
	Telescopes,	Instruments	s & Fo	ocus configu	rations	
	Cass : FORS	9.618 20 – 2.82 20 –	AI	1 Coude VLTI	2.82 20	
UT1	CouA : VLTI CouB : ESPRESSO	2.82 20 2	AI	2 Coude VLTI	2,82 20	JI G1
	NasA : NACO NasB : KMOS	1.8 20 - 7.2 20 -	ΓA	Coude VLTI	2,82 20	J□ J2
	Cass: X-Shooter	20	AI	4 Coude VLTI	2,82 20	K0
UT2	CouA : VLTI CouB : ESPRESSO	2.82 20 2	VIST	A Cass: VIRCAM	100.2 20	
012	NasA : FLAMES	25.2 20	VS	Cass: OmegaCAM	85.2 20	
	NasB : UVES		DIM	Cass : ASM-DIMM	1 20	
	Cass: SINFONI CouA: VLTI	0.18 20 🗖				
UT3	CouB : ESPRESSO	2.82 20 2				
	NasB : CRIRES+					
	Cass: VISIR					
UT4	CouA : VLTI CouB : ESPRESSO	2.82 20 2				
	NasA : HAWK-I NasB : MUSE	13.8 20 T 2.16 20 T			SAVE RESTO	RE
			-			

10 telescopes & 16 instruments and more to come...

ES

What is our tool?

LTCS : the Laser Traffic Collision System



Extension of the VLT Laser Traffic Control System for future collision predictions

Philippe Duhoux, ESO Paranal

a step towards peaceful nights at the VLT

How shall we proceed ?

We will extend the timeline of the collision predictions

The existing features: 1 - From the live-view to 2 - The next observation

The extended features: 3 - The next hours and ultimately 4 - The next semester !

L4A0-13 - Jun 2019



1 - the live-view

Real-time visual and audio notifications ahead of time

Last Updated: 19 Mar 2014 23:56:09

	Observ	atorie	s			Lasers			
			Laser Sensitive		Laser State	Shutter Eve (site,duratio	nt 🚬	redictions umber, site	
UT1	OK	NO	NO			(Site) duratie	,,,,,,	list)	
UT2	OK	NO	YES	UT4	On-Sky	None		1, VST 💻	
UT3	OK	NO	YES			Collision	S		
UT4	OK	NO	NO	Las	er Scope	e Started	Ends	Priority	
VISTA	OK	NO	NO						
VST	OK	NO	YES						
_AT1	OK	NO	NO	La		oviou (Drodi	tions for	Collicions)	
_AT2	OK	NO	NO			eview (Predic			
_AT3	OK	NO	NO	Las	ser Scop	e Starts	Ends	Priority	
_AT4	STALE	NO	NO						
DIMM	OK	NO	NO						

UT4 Collision Prediction(s)

Last Updated: 20 Mar 2014 23:58:07

Field	Value	Units
Involved Telescope	VST	
Laser Has Priority	NO]
Time to Collision	1297]
Duration	3489	Seconds
Start Time	00:19:44 Mar 21 2014 UTC	
End Time	01:17:53 Mar 21 2014 UTC	-
Crossing Distance	28.424	Meters
Crossing Altitude	2676.07	Meters
Angle between Laser & Telescope	59.1733	Degrees
Angle between Laser & Separation Vector	101.871	Degrees

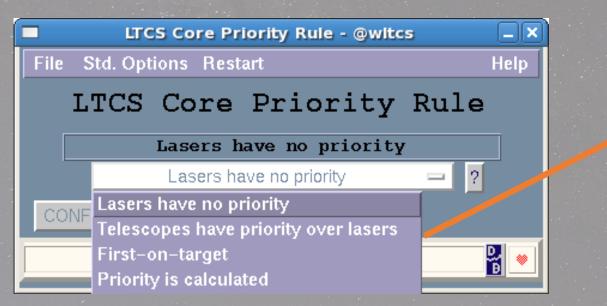


Collision status as of the actual positions of the telescopes against the laser emitting telescope(s)



1 - handling priorities

Not all telescopes have the same priority at all times



At equal priority, First-on-Target scheme prevails

	Core Priority Rule - @w	itcs 🔤 🗙
File Std. Options		Help
LTCS Laser	/ Telescope	Priorities
ULTI-AT	ULTI-UT	
AT1 NORMAL 📼	UT1 HIGH 💻	
AT2 NORMAL ==	UT2 NORMAL 💳	VST NORMAL =
AT3 NORMAL -	UT3 HIGH 💻	DIMM NORMAL 📼
AT4 NORMAL 📼	UT4 NORMAL 📼	E-ELT NORMAL 📼
Lase	r UT4 NORMAL 💳 🛛 La	iser EELT NORMAL 📼
	APPLY	
		8

HIGH: Visitor mode NORMAL: Service mode LOW: Commissioning, Technical



2 - What if one would execute this observation now ?

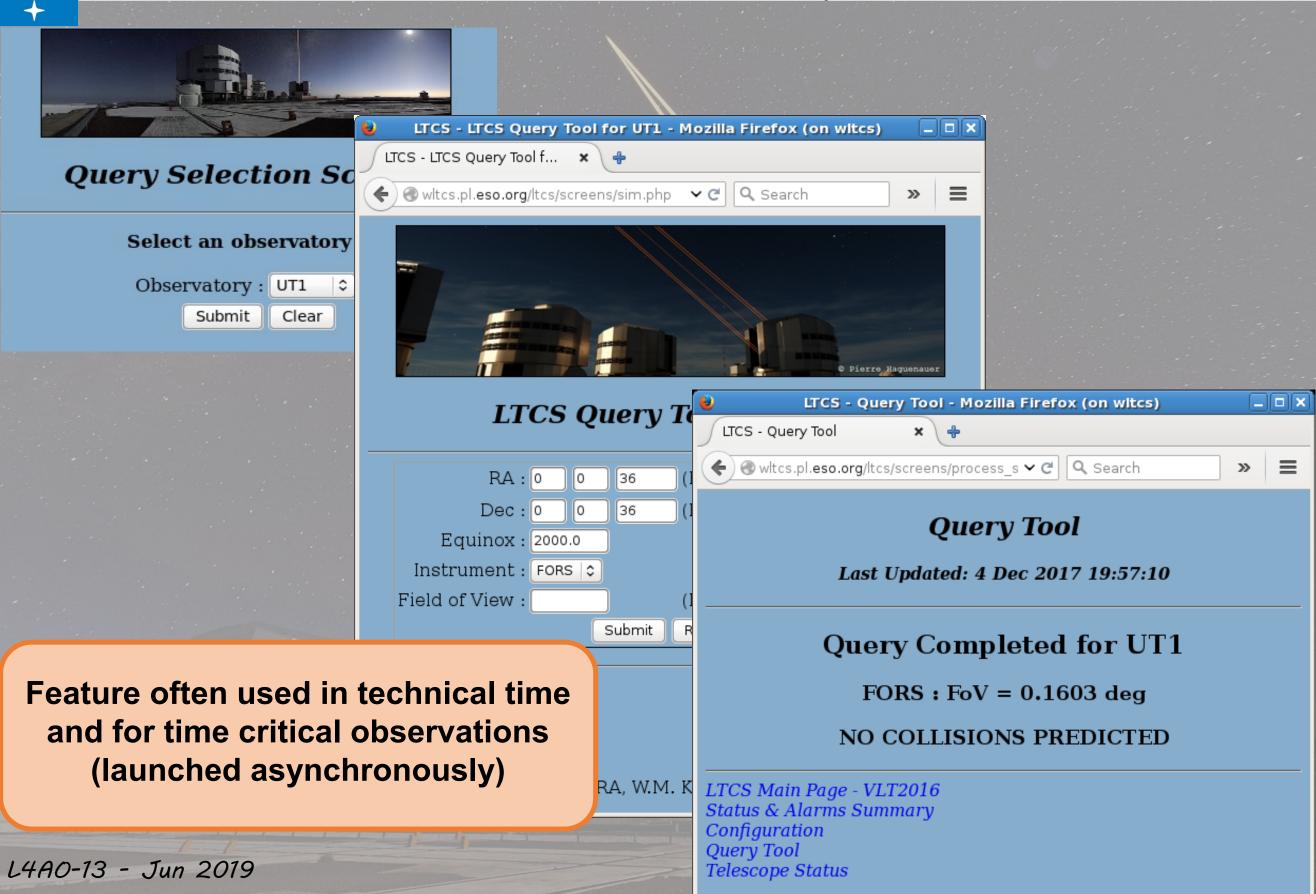
Query the collision status assuming the telescopes are not changing their observing line of sight

Handling priorities: Night staff needs to exchange information Special cases Possible conflicts



Collision status always as of the actual positions of the telescopes against the laser emitting telescope(s)

2 - manual queries



2 - automatic queries in visitor and service modes

e Queues		ling Charts Readm	e cpne							
OT Queues										
Execution Se	equence All Q	ueues Open Queu	ues							
		Мо	ove To To	p Move Up Mo	ove Down Di	play Finding Chart	s View Display	Text Collision c	heck	
OB ID	Container ID	Prog.ID	Status	Laser Sensitive	Container	Requests Laser	RA	OB comment	Inst comment	OB name
138845		094.B-0895(A)	+	\checkmark			03:38:08.480	Yes	No	WFM NGC1396E 2
43377		60.A-9800(D)		\sim			16:23:33.750	No	No	efficiency mon dic2 EG274
62645	962639	091.D-0633(A)		\checkmark	0		03:49:11.220	Yes	Yes	pleioneC
.005235	1023057	092.C-0290(A)		\checkmark	C		04:33:52.005	Yes	Yes	CITau
.023061	1023057	092.C-0290(A)		\checkmark	С		06:08:55.820	Yes	Yes	CAL Hip029147-Tstd citau
43383		60.A-9800(D)	+	\checkmark			20:10:56.845	No	No	efficiency mon dic2 LTT798
.023068	1023064	092.C-0290(A)	+	\checkmark	C		04:20:30.380	Yes	Yes	CAL Hip020258-Tstd dntau
.005238	1023064	092.C-0290(A)		\checkmark	C		04:35:27.375	Yes	Yes	DNTau
43379		60.A-9800(D)		\checkmark			23:19:58.390	No	No	efficiency mon dic2 Feige1
43381		60.A-9800(D)		\checkmark			08:41:32.400	No	No	efficiency mon dic2 LTT321
.019881		092.D-0295(A)		\checkmark			05:15:38.479	No	Yes	CEP506 15
.005241	1023071	092.C-0290(A)		~	C		04:18:40.616	Yes	Yes	V892Tau
.023075	1023071	092.C-0290(A)					04:23:59.760	Yes	Yes	CAL Hip020533-Tstd V892
.005247	1023087	092.C-0290(A)		· · ·	ŏ		04:19:41.272	Yes	Yes	LkCa7
.023088	1023087	092.C-0290(A)			ă		04:23:59.760	Yes	Yes	CAL Hip020533-Tstd LkCa
.023066	1023049	092.C-0290(A)		×.	ă		04:20:30.380	Yes	Yes	CAL Hip020353-Tstd LkCa
.025035	1023049				ă		04:38:28.580	Yes	Yes	DOTau
.005232		092.C-0290(A)		•	ă					
	1049114	093.B-0615(A)		• • • • • • • • • • • • • • • • • • •			12:54:54.560	Yes	Yes	outerhalo08 5
.049716	1053804	093.C-0929(D) 093.D-0415(A)		• • • • • • • • • • • • • • • • • • •	0		22:57:27.850 08:24:57.207	Yes Yes	Yes Yes	51Peg 17 hip41250 2
032009	1033604	095.D-0415(A)	Ŧ	×	U		00.24.37.207	162	162	111041230 Z
(33333								
				Collision ch	neck done <	-> Date: Thu Mar 05	16:44:17 GMT 20	15		
Collision De	etails Ob Tree	View							_	
OB ID: 7433						Best ran	ked ob	servat	tions a	re checked
							fornor	cibla	olligio	NDC
Collision che	ecked on: 2015-	03-05T16:44:03 UTC					for pos	SINIE (2011210	115
OB collision	status: COLLISI	ION NOW					•			
						Every Q	ls on	chang	and a	on demand
		COLLIS	SIONS				5 , 01	unang		
S	Start	End		Laser telescope	Telescope Pr	iority				
2015-03-05	5T16:44:02 UTC	2015-03-05T17:14:	02 UTC	UT4	UT1	UT4				
2015-03-05	5T18:44:02 UTC	2015-03-05T19:44:	02 UTC	UT4	UT1	JT4				

+ES

2 - Humans have the last word!

	Move To Top	Move Up Mov	e Down Display	Finding Cha	rts View	Display Te:	xt Collision check	<mark>k</mark>	1. 1.
OB na	me	Container ID	Prog.ID	Status	Lase	r Sensitive	Requests Laser	OB comment	Inst
MACSJ0150_10	05_C_02_pr	1193090	095.B-0721(A)	+		\checkmark		Yes	No
HD140538_UV	ES580_SimC		60.A-9022(B)	M		\sim		No	No
FLAMES_IFUstd	Feige66		60.A-9022(B)	S				Yes	No
j1452			094.C-0202(A)	+		\sim		Yes	Yes
_		1135867	094.A-0765(A)	+		\sim		Yes	Yes
TARGET2_2	TARGET2_2		095.D-0843(A)	+		_ √		No	Yes
SkyFlat UBVRI 1			60.A-9022(C)			\checkmark		No	No
MACSJ0150_10		1193090	095.B-0721(A)			_ √		Yes	Yes
MACSJ0150_10	05_C_02_p	1193090	095.B-0721(A)	+		\sim		Yes	No
ils Ob Tree Vie	w		<u>Y</u> es	<u>N</u> o					
75 cked on: 2015-0 status: PREDICTEI lision status [11	COLLISION(s)		(S)					always reo Id be caus	-
	(OLLISIONS							
itart		End	Laser telescope	Telescope	Priority				
2T11:41:18 UTC	2015 04 02	T13-15-53 UTC	шти	117.5	117.4				
LI II. 41. 10 OIC	2015-04-02	T12:15:53 UTC	UT4	UT2	UT4				$\lambda_{\rm max}$

+ES+

3 - What about the next hours ?

But that does not guaranty a peaceful night !

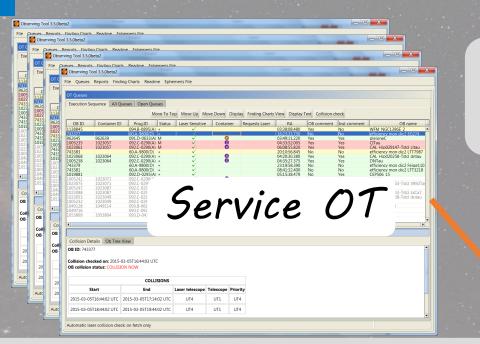
WHY ?

Because the problem repeats for each OB of each telescope

AND WHAT CAN WE DO ?

So one needs to prepare a scheduling overview valid over the next hours

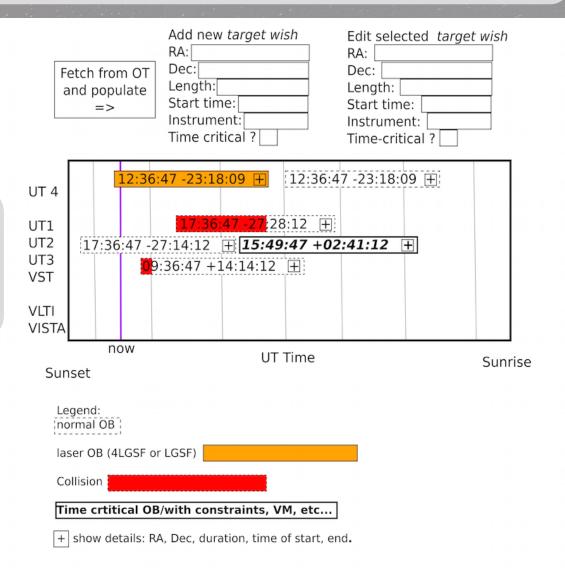
3 - Dynamic overview of the night



Analyze the execution sequences of all telescopes (from OT & vOT) Every 90s / on change



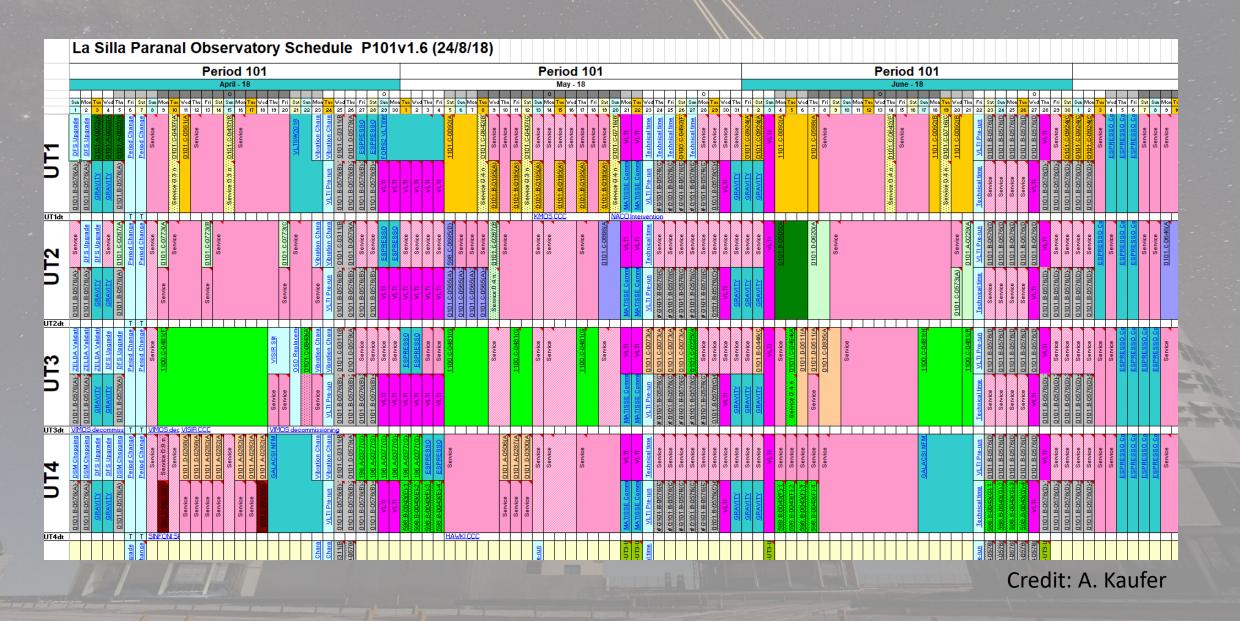
Mock-up display of the timeline and highlight predicted collisions



Iterate on the order of the OBs in the execution sequences



Reducing the collision cases and conflictual situations to the minimum

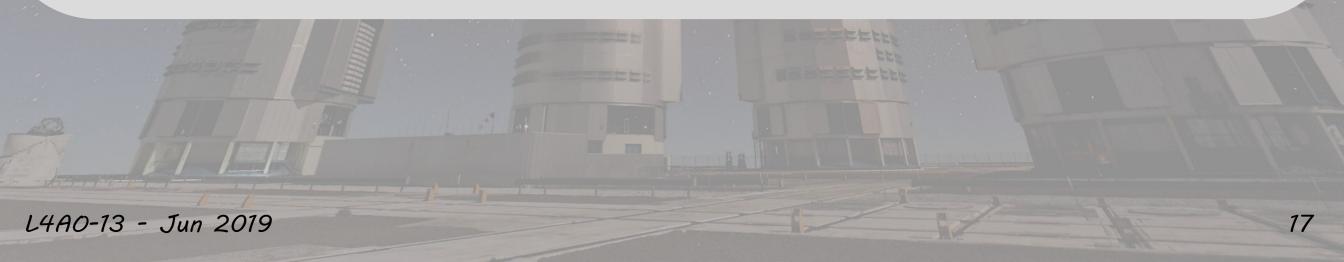




Conclusions

1 – Live-view: Operator is informed in real-time of collisions (ahead of time)

- 2 Queries: Always considering the actual positions of the telescopes Communication between Night Operators & Astronomers, Gentleman agreement when visitors conflict
- 3 Scheduling: a step towards more peaceful nights Fully dynamic overview for the next hours Minimizing the collision cases at observatory level
- 4 Planning: Collision / conflictual situations reduced to minimum





and the timeline

Requirements review on-going

Deliveries: Step 3 for Apr 2020 Step 4 for Oct 2019